

## Trendline RE motor PROGRAMING

(only Trendline emitters work with this motor)

**Add the emitter:** after power cut off (or push the red button on the motor head for a sec) push down together the UP and DOWN buttons on the emitter, than after this push the STOP button once. The learning is finished.

**Changing the direction** (if necessary): push down the red button on the motor head and keep pushing till the motor moved little up-down (after 2 sec around).

**Delete the emitter:** push down together the UP and DOWN buttons on the emitter, than after this push the STOP button 7X times, and after that 1X the UP button. The emitter is deleted now.

**Add another emitter:** same method as the original learning.

**Set the UP limit:** move the slats the UP position where we want the UP limit. Now push down together the UP and DOWN buttons on the emitter, than after this push the STOP button 2X and 1X the UP button. The learning is finished.

**Set the DOWN limit:** move the slats the DOWN position where we want the DOWN limit. Now push down together the UP and DOWN buttons on the emitter, than after this push the STOP button 2X and 1X the DOWN button. The learning is finished.

**If You want to delete end limit:** move the slats somewhere middle and push down together the UP and DOWN buttons on the emitter, than after this push the STOP button 4X and 1X the UP or DOWN button (which one we want to delete). Now we deleted that end limit and we can set a new one.

**Setting the obstacle detection...**always do it!!! Push down together the UP and DOWN buttons on the emitter, than after this push the STOP button 3X and than the UP button 1X. Now the obstacle detection is working (always use anti push up device).

Normally the the motor only stops when it feels obstacle. If You want to **rebound** as well (we recommend) do this: Push down together the UP and DOWN buttons on the emitter, than after this push the STOP button 3X .

**Set a middle (favourite position):** go that position and push the STOP button 4X times. Now You can call this position from anywhere if You keep pushing the STOP button (for 3 sec).